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Kernel-Smoothed Conditional Quantiles of
Correlated Bivariate Discrete Data

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Abstract: Socio-economic variables are often measured on a discrete scale or rounded to protect confidentiality. Nevertheless, when exploring the effect of a relevant covariate on the outcome distribution of a discrete response variable, virtually all common quantile regression methods require the distribution of the covariate to be continuous. This paper departs from this basic requirement by presenting an algorithm for nonparametric estimation of conditional quantiles when both the response variable and the covariate are discrete. Moreover, we allow the variables of interest to be pairwise correlated. For computational efficiency, we aggregate the data into smaller subsets by a binning operation, and make inference on the resulting prebinned data. Specifically, we propose two kernel-based binned conditional quantile estimators, one for untransformed discrete response data and one for rank-transformed response data. We establish asymptotic properties of both estimators. A practical procedure for jointly selecting band- and binwidth parameters is also presented. Simulation results show excellent estimation accuracy in terms of bias, mean squared error, and confidence interval coverage. Typically prebinning the data leads to considerable computational savings when large datasets are under study, as compared to direct (un)conditional quantile kernel estimation of multivariate data. With this in mind, we illustrate the proposed methodology with an application to a large dataset concerning US hospital patients with congestive heart failure.

Key words and phrases: Binning, Bootstrap, Confidence interval, Jittering, Nonparametric.

1. Introduction

Nonparametric estimation of the conditional cumulative distribution function (CDF) of a response variable given a covariate has been well studied for continuous data. Given a sample conditional CDF, sample conditional quantiles are often computed to characterize the distribution. There are situations, however, where it is necessary to calculate sample conditional quantiles from data

having a discrete distribution. For example, in studying the relationship between monthly unemployment spell and experience-education profile (in years), policymakers want to know whether higher education reduces unemployment spell between the 25th and 75th quantiles of the response variable as a function of the covariate. Another example concerns the need for better management of hospital care by describing the shape of the conditional distribution of the length of hospital stay, a variable often considered as a measure of patients' recovery, given covariates like patients age, sex, gender, ethnicity, or severity of disease.

Methods for *un*conditional quantile estimation for discrete data have been proposed by González-Barrios and Rueda (2001), Chen and Lazar (2010), and Frydman and Simon (2007), among others. Machado and Santos Silva (2005) introduced a variant of quantile regression for mixed discrete-continuous variables. More recently, Li and Racine (2008) considered nonparametric estimation of conditional CDFs for mixed discrete (categorical)–continuous random variables. The latter two approaches are restricted by the continuous assumption of the covariates but, as with the examples above, in practice there may not exist continuously distributed covariates. In this paper we consider a setting where both the response variable and the covariate are assumed discrete. Moreover, we allow the variables of interest to be pairwise correlated. For efficient and effective smoothing, we aggregate the data into smaller subsets by a binning operation, and make inference on the resulting prebinned data. This set-up may offer new insights as to the nature of the relationship between a response and potential covariates, possibly with interesting implications to the issue at hand.

As an illustration, Figure 1 displays a scatterplot of a discrete-valued response variable "Length of hospital stay" (in days) versus "Severity of disease" (measured on a 7-point scale) for a dataset of $20,631$ patients; see Section 7 for more details. In addition, Figure 1 shows some selected conditional percentiles using a "naive" method that takes the data as continuous. Kendall's rank correlation coefficient indicates, at a two-tailed significance level of 1%, that the variables are positively correlated. Note that the conditional percentiles diverge noticeably toward the high end of the severity scale. For instance, the interquartile range at the value 5 of the covariate, is 8 days, it is 22 days when the covariate takes the value 7. On the other hand, when unconditional percentiles are com-
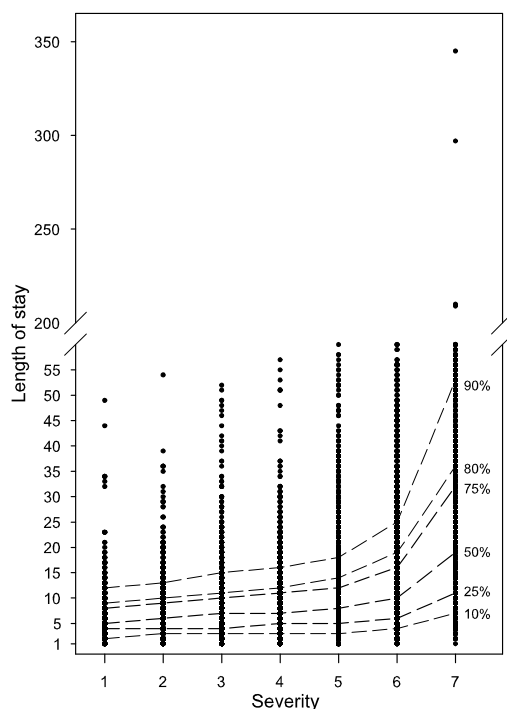
Figure 1. Some selected population conditional percentiles for the discrete-valued response variable "Length of hospital stay" versus the covariate "Severity of disease", based on 20,631 observations.

puted, ignoring correlations between the response variable and the covariate, the interquartile range of the response variable is 10 days. Clearly the conditional percentiles convey more information about the data than do unconditional percentiles.

Note that the above dataset is large, which is common in many areas of science. In analysing large sample sizes n one often needs to reduce the amount of storage space and computing time. Thus, computing a standard kernel-smoothed density estimator at m evaluation points for continuously distributed data requires nm kernel evaluations; see, e.g., Fan and Marron (1994). A number of methods are available to address this problem, and most work with the idea of binning the data first. The binning operation leads to substantial computational savings since calculations are based on the number of bins, rather than the num-

ber of data points, with the total number of operations directly proportional to the expected number of nonempty bins. Moreover, it has been shown (cf., González-Manteiga, Sánchez-Sellero, and Wand (1996), and Holmström (2000)) that the estimation error of the binned kernel-smoothed density estimator is essentially the same as that of the standard kernel estimator for continuous data.

With a strong view toward analysing large datasets, we propose a kernel-based, nonparametric approach to conditional quantile estimation of correlated discrete bivariate data by binning the response variable. Binning has been studied in the case of unconditional kernel-based density estimation and local polynomial kernel estimation of continuous data. Its application to estimating conditional quantiles for data from bivariate discrete distributions has not been a topic of research, as far as we know. While binning can be viewed as providing a discrete approximation to the continuum, our use of binning brings in data under study. In that sense, the binning is well motivated.

With discrete variables asymptotic theory breaks down due to the fact that the sample conditional CDF is not absolutely continuous with respect to Lebesgue measure. To circumvent this problem we propose a conditional quantile estimator by linearly interpolating between the jumps of the conventional binned sample CDF. In fact, we consider two variants of the estimator: one for untransformed discrete data, and one that can be used for rank-transformed response data. In both cases we establish, under mild regularity conditions, asymptotic normality and consistency. In addition, we formulate a data-driven algorithm for jointly selecting the band- and binwidths of the proposed conditional quantile estimators.

The paper proceeds as follows. In Section 2, we present the binning principle in its simplest form. In Section 3, we define two binned kernel-based conditional quantile estimators, and Section 4 presents their asymptotic properties. Various practical issues related to the two estimators are discussed in Section 5. In Section 6 we provide numerical simulations of the performance of the estimators for correlated bivariate discrete random variables. Section 7 contains an illustration with data. Finally, Section 8 presents some concluding remarks. We relegate all technical arguments to an Appendix.

2. Binning

Let $Z = \{Z_1, \ldots, Z_n\}$ be a dataset in $[a, b]$ ($-\infty < a < b < \infty$). To bin

the data, we divide the support set into M intervals (bins) $\{\mathcal{A}_j\}_{j=1}^M$, with $\mathcal{A}_j = [a_{j-1}, a_j)$ $(j = 1, \ldots, M-1)$, $\mathcal{A}_M = [a_{M-1}, a_M]$, and $a = a_0 < a_1 < \cdots < a_M = b$. For notational simplicity, take the lengths of the intervals (binwidths), $\delta = (a_j - a_{j-1})$ to be fixed across the intervals. We refer to $g_\ell \equiv \ell\delta$ $(\ell = 0, 1, \ldots, M)$ as grid points. Then a binning rule in its simplest form may be represented by a sequence of weights $\{w_\ell(z, \delta); \ell = 0, 1, \ldots, M\}$, with $\sum_{\ell=0}^M w_\ell(z, \delta) = 1$, such that the data are replaced by the weights attached to each grid point according to a certain rule. Thus a new data value is created as $c_\ell(z) = \sum_{i=1}^n w_\ell(Z_i, \delta)$ (grid count) at grid point g_ℓ. Here we adopt linear binning (Jones and Lotwick (1983)) for which

$$c_\ell(z) = \sum_{i=1}^n (1 - |\delta^{-1} Z_i - \ell|)^+, \tag{2.1}$$

with $x^+ = \max(0, x)$. Thus, data values Z_i closer to g_ℓ contribute more weight, while Z_i's with distance $> \delta$ contribute zero weight. Hall and Wand (1996) showed that, in terms of approximation error, linear binning is more accurate than simple binning, where each observation is assigned to its nearest grid point.

3. Binned Conditional Quantiles for Discrete Distributions
3.1 Untransformed data

Our analysis concerns a pair of random variables X (covariate) and Y (response) taking values in the space $\mathbb{N}_1 \times \mathbb{N}_0$ according to a joint probability distribution function $F(x, y) = \Pr(X \le x, Y \le y)$, with $\mathbb{N}_1$ the set of positive integers and $\mathbb{N}_0$ the set of non-negative integers. Then the α-conditional quantile $(\alpha \in (0, 1))$ is the value $\theta_\alpha(x)$ that solves $F(\theta_\alpha(x)|x) = \alpha$, where $F(y|x) = \Pr(Y \le y|X = x)$, or alternatively $\theta_\alpha(x) = \min_{\eta \in \mathbb{N}_1}\{F(\eta|x) \ge \alpha\}$. Let $(X_1, Y_1), \ldots, (X_n, Y_n)$ denote a random sample of size n from $F(x, y)$. Assume that the raw data $\{Y_i\}$ are arranged in increasing order, giving rise to the data $\{Y_{(1)}, \ldots, Y_{(n)}\}$ with $\{\tilde{X}_i\}$ denoting the corresponding rearranged X_i's.

To obtain a binned estimator of $F(y|x)$, the dataset $\{\tilde{X}_i, Y_{(i)}\}$ is split up into m disjoint subsets with m denoting the number of distinct values x_u^* $(u = 1, \ldots, m)$ taken on by the X_i's $(i = 1, \ldots, n)$. Suppose a subset contains $n_u = \sum_{i=1}^n I(\tilde{X}_i = x_u^*)$ $(n_u > 0; u = 1, \ldots, m)$ observations, with $I(A)$ the indicator function for set $\{A\}$. In addition, let the grid count at grid point g_ℓ, conditioning

on the covariate $X = x_u^*$ $(u = 1, \ldots, m; \ell = 0, 1, \ldots, M-1)$, be given by

$$c_{u,\ell}(y|x) \quad = \quad \sum_{i=1}^{n} I(\tilde{X}_i = x_u^*)(1 - |\delta^{-1}Y_{(i)} - (\ell-1)|)^+. \qquad (3.1)$$

Note that (3.1) is a rescaled version of (2.1) with $I(\tilde{X}_i = x_u^*)$ representing the conditioning on $X = x$ in $F(y|x)$. The rescaling allows for the case $c_{u,0}(y|x) = 0$. Given (3.1), and assuming $n_u \neq 0$, the relative cumulated grid counts at each grid point g_ℓ conditional on each value x_u^* can be computed.

The basic idea is to position the bin weights in a matrix with rows corresponding to bins and columns to conditioning values, and then to kernel smooth the rows. This requires three steps. Summarize the relative cumulated grid counts $c_{u,\ell}(\cdot)$ into an $M \times m$ matrix $\boldsymbol{C}$ with

$$C_{v,u}(y|x) = \begin{cases} 0 & \text{if} \quad u = 1, \ldots, m; v = 1, \\ \frac{1}{n_u}\sum_{\ell=1}^{v-1} c_{u,\ell}(y|x) & \text{if} \quad u = 1, \ldots, m; v = 2, \ldots, M. \end{cases}$$

Next, compute an $m \times m$ kernel weighting matrix $\boldsymbol{W}$ with

$$W_{u,j}(h) = \frac{n_u K_d((x_j - x_u^*)/h)}{\sum_{u=1}^{m} n_u K_d((x_j - x_u^*)/h)},$$

where $K_d(\cdot)$ is a discrete kernel function on the ordered set $[1, \infty]$, with bandwidth h $(h \in \mathbb{N}_1)$. Finally, multiply $\boldsymbol{C}$ and $\boldsymbol{W}$ to obtain an $M \times m$ matrix $\boldsymbol{CW}$ with binned kernel-smoothed empirical conditional CDFs, and with (v, j)th element $(v = 1, \ldots, M; j = 1, \ldots, m)$ given by

$$F_n(y|x) = \frac{1}{\sum_{u=1}^{m} n_u K_d((x_j - x_u^*)/h)} \sum_{u=1}^{m} n_u K_d((x_j - x_u^*)/h) C_{v,u}(y|x). \quad (3.2)$$

Note (3.2) may be considered as a binned discrete analogue of the Nadaraya-Watson conditional CDF estimator when (X, Y) is continuously distributed.

Using (3.2), it may be shown that the binned conditional quantile estimator is not consistent if α is at a plateau of $F(y|x)$, i.e. $F(y|x) = \alpha$ and $F(y|x)$ is flat in a right-neighborhoud of $\theta_\alpha(x)$; see Section 4. A way around this difficulty is to define a new conditional CDF, say $\tilde{F}(y|x)$, from $F(y|x)$ by linear interpolation at successive grid points:

$$\tilde{F}(y|x) = F(g_L|x) + \left(\frac{y - g_L}{\delta}\right)\left[F(g_{L+1}|x) - F(g_L|x)\right], \qquad (3.3)$$

where L is chosen such that $g_L \leq y < g_{L+1}$. The corresponding conditional quantile is then $\theta_\alpha^c(x) = \inf_{\eta \in \mathbb{R}} \{ \tilde{F}(\eta|x) \geq \alpha \}$, where the superscript c highlights the fact that (3.3) is a continuous CDF (see Section 4 for our choice of interpolation).

Given (3.3), and making use of (3.2), an estimator $F_n(y|x)$ of $\tilde{F}(y|x)$ at a general point x_u^* $(u = 1, \ldots, m)$, can be obtained as a linear interpolation between successive grid points. More precisely, the binned kernel-smoothed empirical conditional CDF is

$$\tilde{F}_n(y|x_u^*) = F_n(g_L|x_u^*) + \left(\frac{y - g_L}{\delta} \right) \Big[F_n(g_{L+1}|x_u^*) - F_n(g_L|x_u^*) \Big]. \tag{3.4}$$

Hence the binned smoothed conditional quantile estimator of $\theta_\alpha(x)$ is defined by

$$\hat{\theta}_\alpha^c(x_u^*) = \begin{cases} \left(\frac{\alpha - F_n(g_L|x_u^*)}{F_n(g_{L+1}|x_u^*) - F_n(g_L|x_u^*)} \right) g_L \\ \quad + \left(\frac{F_n(g_{L+1}|x_u^*) - \alpha}{F_n(g_{L+1}|x_u^*) - F_n(g_L|x_u^*)} \right) g_{L+1}, & \text{if } n_u \neq 0, \\ \theta_0 & \text{if } n_u = 0, \end{cases} \tag{3.5}$$

where θ_0 is an arbitrary value, and where L is chosen such that $\sum_{v=1}^{L} F_n(g_v|x_u^*) \leq \alpha < \sum_{v=1}^{L+1} F_n(g_v|x_u^*)$.

The binned conditional quantile estimator $\hat{\theta}_\alpha(\cdot)$ of $F(y|x)$ can be obtained from (3.5) by using the transformation

$$\hat{\theta}_\alpha(x_u^*) = \lceil \hat{\theta}_\alpha^c(x_u^*) - 1 \rceil, \tag{3.6}$$

where $\lceil \cdot \rceil$ is the ceiling function that returns the smaller integer greater than, or equal to its argument; see Machado and Santos Silva (2005, Theorem 2). Clearly, the advantage of binning stems essentially from the fact that the grid counts need to be computed only once.

3.2 Rank-transformed data

In practice one may encounter a situation with highly skewed empirical conditional CDFs (see Section 7). This gives rise to many empty bins and a few bins containing a large proportion of the observations. A rank transformation of Y_i avoids this problem. Hence, we now introduce a binned conditional quantile estimator for rank-transformed discrete-valued data. The proposed estimator is similar in spirit to the kernel-smoothed binned conditional quantile estimator for bivariate continuously distributed random variables introduced by Magee, Burridge, and Robb (1991).

Ranks can be assigned to data in several ways. Here, we rank the entire set of observations $\{Y_i\}$ from smallest to largest, giving rise to the dataset $\{R_1, \ldots, R_n\}$ with $\{\tilde{X}_i\}$ the corresponding rearranged X_i's. In the case of ties we order tied observations at random. Then, following the same setup as introduced in Subsection 3.1, the dataset $\{\tilde{X}_i, R_i\}$ is split up into m disjoint subsets each containing n_u $(u = 1, \ldots, m)$ observations. From the ranking of the response data we conclude that $g_0 = 0$ and $g_M = n + 1$. Then, similar to (3.1), we assume that the grid count at grid point g_ℓ, conditioning on the covariate $X = x_u^*$ $(u = 1, \ldots, m; \ell = 0, 1, \ldots, M - 1)$, is given by

$$\tilde{c}_{u,\ell}(y|x) \;=\; \sum_{i=1}^n I(\tilde{X}_i = x_u^*)(1 - |\delta^{-1}R_i - (\ell - 1)|)^+, \qquad (3.7)$$

where $\delta = (n+1)/M$ denotes the corresponding binwidth. Thus, in analogy with (3.2), a typical element of the $M \times m$ matrix $\boldsymbol{CW}$ with binned rank-transformed empirical CDFs is given by

$$F_n^R(y|x) \;=\; \frac{1}{\sum_{u=1}^m n_u K_d((j-u)/h)} \sum_{u=1}^m n_u K_d((j-u)/h)\tilde{C}_{v,u}(y|x), \quad (3.8)$$

where

$$\tilde{C}_{v,u}(y|x) = \begin{cases} 0 & \text{if } u = 1, \ldots, m; v = 1, \\ \frac{1}{n_u} \sum_{\ell=1}^v \tilde{c}_{u,\ell}(y|x) & \text{if } u = 1, \ldots, m; v = 2, \ldots, M. \end{cases}$$

Using (3.8), the αth smoothed conditional quantile estimator $\tilde{\theta}_\alpha(x_u^*)$ for the binned rank-transformed data, at a general point x_u^* $(u = 1, \ldots, m)$, can be obtained as a linear interpolation between two known successive grid points. More precisely, the binned kernel-smoothed empirical conditional CDF is given by

$$\tilde{F}_n^R(y|x_u^*) = F_n^R(y|x_u^*) + \left(\frac{y - g_L}{g_{L+1} - g_L}\right)[F_n^R(y+1|x_u^*) - F_n^R(y|x_u^*)], \qquad (3.9)$$

where L is such that $g_L < y < g_{L+1}$, and $y + 1$ denotes the smallest rank in the data bigger than y. Hence, the binned kernel-smoothed quantile estimator for the rank-transformed observations is given by

$$\tilde{\theta}_\alpha(x_u^*) = \begin{cases} \left(\frac{\alpha - F_n^R(y|x_u^*)}{F_n^R(y+1|x_u^*) - F_n^R(y|x_u^*)}\right)g_L \\ + \left(\frac{F_n^R(y+1|x_u^*) - \alpha}{F_n^R(y+1|x_u^*) - F_n^R(y|x_u^*)}\right)g_{L+1} & \text{if } n_u \neq 0, \\ \theta_0 & \text{if } n_u = 0, \end{cases} \qquad (3.10)$$

where L is chosen such that $\sum_{v=1}^{L} F_n^R(y|x_u^*) \le \alpha < \sum_{v=1}^{L+1} F_n^R(y|x_u^*)$, and θ_0 is an arbitrary value. Transforming (3.10) back into the original observations, and assuming $n_u \neq 0$, results in the following binned kernel-smoothed estimator of $\theta_\alpha(x_u^*)$:

$$
\begin{aligned}
\tilde{\theta}_\alpha^{Y}(x_u^*) &= [1 - (\tilde{\theta}_\alpha(x_u^*) - \lfloor \tilde{\theta}_\alpha(x_u^*) \rfloor)] \tilde{Y}_{(u, \lfloor \tilde{\theta}_\alpha(x_u^*) \rfloor)} \\
&\quad + (\tilde{\theta}_\alpha(x_u^*) - \lfloor \tilde{\theta}_\alpha(x_u^*) \rfloor) \tilde{Y}_{(u, \lfloor \tilde{\theta}_\alpha(x_u^*) \rfloor + 1)},
\end{aligned}
\tag{3.11}
$$

where $\lfloor \cdot \rfloor$ is the floor function returning the greatest integer less than or equal to its argument, and where $\{\tilde{Y}_{(u,1)}, \ldots, \tilde{Y}_{(u,n_u)}\}$ is the ordered (increasing order) values of $\{Y_i\}$ when $\tilde{X}_i = x_u^*$ $(i = 1, \ldots, n; u = 1, \ldots, m)$. Then, similar to the transformation in (3.6), the discrete conditional binned quantile estimator of $\theta_\alpha(\cdot)$ is given by

$$
\tilde{\theta}_\alpha(x_u^*) = \lceil \tilde{\theta}_\alpha^{Y}(x_u^*) - 1 \rceil.
\tag{3.12}
$$

4. Asymptotic Results

To study the asymptotic properties of $\hat{\theta}_\alpha(\cdot)$ we use the method of jittering; see, e.g., Machado and Santos Silva (2005). With this method, a continuous distribution is constructed which coincides with the discrete distribution up to interpolation. Asymptotic properties of the conditional quantile estimator in the continuous case are easily obtained using existing theory, and then asymptotic results for the discrete case follow from (3.6). Asymptotic properties of (3.12) are based on theorems for linear rank statistics given by Hájek, Šidák, and Sen (1999).

4.1 Untransformed data

Without loss of generality, we take the support of $Y|x$ as composed of consecutive integers in $\{0, 1, 2, \ldots\}$. Let $p_i = P(Y = y_i|x)$ and $P_j = P(Y \le y_j|x) = \sum_{i \le j} p_i$. We add small jitters e_i to Y_i, $Z_i = Y_i + e_i$ $(i = 1, \ldots, n)$, say, where the e_i are independent uniforms on $[0, 1]$. If $F_J(z|x)$ is the distribution of the Z_i's, then $F_J(k|x) = F(k|x)$, $(k = 0, 1, 2, \ldots)$. Here $F_J(\cdot|x)$ is a continuous distribution that linearly interpolates $F(\cdot|x)$, and $\tilde{F}(y|x)$ given in (3.3) is exactly the conditional distribution function of the binned version based on the Z_i's, $F_n(y|x)$

in (3.4) is the corresponding empirical version, $\hat{\theta}_\alpha^c(\cdot)$ is the corresponding conditional quantile estimate, and the relationship between $\hat{\theta}_\alpha(\cdot)$ and $\hat{\theta}_\alpha^c(\cdot)$ is given in (3.6).

As in Cheng and Lazar (2010), we consider two cases.

(i) $P_{k-1} < \alpha < P_k$ for some $k \in \{1, 2, \ldots\}$, α is not at a plateau of $\tilde{F}(\cdot|x)$. Using results for continuous distribution, we have $\hat{\theta}_\alpha^c(\cdot) \overset{a.s.}{\to} \theta_\alpha^c(\cdot)$ and, since the function $\lceil t - 1 \rceil$ is continuous at $t = \theta_\alpha^c(\cdot)$, consequently we have $\hat{\theta}_\alpha(\cdot) = \lceil \hat{\theta}_\alpha^c(\cdot) - 1 \rceil \overset{a.s.}{\to} \lceil \theta_\alpha^c(\cdot) - 1 \rceil = \theta_\alpha(\cdot)$.

(ii) If $\alpha = P_k$ for some k, then $\theta_\alpha(\cdot)$ is an integer, the function $\lceil t - 1 \rceil$ has a jump at $t = \theta_\alpha(\cdot)$. Consequently, although $\hat{\theta}_\alpha^c(\cdot) \overset{a.s.}{\to} \theta_\alpha^c(\cdot)$, $\lceil \hat{\theta}_\alpha^c(\cdot) - 1 \rceil \overset{a.s.}{\to} \lceil \theta_\alpha^c(\cdot) - 1 \rceil$ fails because of the discontinuity. So for such α, $\hat{\theta}_\alpha(\cdot)$ is not consistent for $\theta_\alpha(\cdot)$. As implied in Serfling (1980, p. 77), in this case, for large n, $\hat{\theta}_\alpha(\cdot) \geq \theta_\alpha(\cdot) + 1$ with probability approximately 0.5.

The theoretical results are derived under the following assumptions.

A.1 $h = h_n \to 0$ and $\sum_{n \geq 1} \exp(-Cnh_n) < \infty$ for all $C > 0$.

A.2 $\delta = \delta_n \to 0$.

A.3 $K(\cdot)$ has bounded continuous third derivative.

A.4 $h = o(n^{-1/5})$ and $\delta = O((nh)^{-1/4})$.

Let $\overset{L_2}{\to}$ stands for convergence in squared mean, $\overset{D}{\to}$ for convergence in distribution, $B(p)$ is the Bernoulli distribution with $p = P(X = 1)$, $p(x)$ is the pmf of X, and $p(x, y)$ is the joint pmf of (X, Y).

Theorem 1. *Under A.1–A.3, as $n \to \infty$, we have $\sup_y E(F_n(y|x) - F(y|x))^2 \to 0$ and $\sup_y E(\tilde{F}_n(y|x) - \tilde{F}(y|x))^2 \to 0$.*

Theorem 2. *Under A.1–A.3, as $n \to \infty$, we have*
(i) $\hat{\theta}_\alpha^c(x) \overset{L_2}{\to} \theta_\alpha^c(x)$, $\forall \alpha \in (0, 1)$;
(ii) $\hat{\theta}_\alpha(x) \overset{L_2}{\to} \theta_\alpha(x)$, $\forall \alpha \in (0, 1) \setminus \{P_k : k \in \mathbb{N}_0\}$.

Theorem 3. *Under A.3 and A.4, as $n \to \infty$, the following hold.*
(i) $\forall \alpha \in (0, 1) \setminus \{P_k : k \in \mathbb{N}_0\}$,

$$\sqrt{nh}(\hat{\theta}_\alpha^c(x) - \theta_\alpha^c(x)) \overset{D}{\to} N(0, \sigma^2), \qquad (4.1)$$

with $\sigma^2 = \alpha(1-\alpha)p(x)\int K^2(v)dv/p^2(x,\theta_\alpha^c(x))$.

(ii) If $\alpha = P_k$ for some $k \in \mathbb{N}_1$,

$$\sqrt{nh}(\hat{\theta}_\alpha^c(x) - \theta_\alpha^c(x)) \xrightarrow{D} N^+(0, \sigma_{k,+}^2) + N^-(0, \sigma_{k,-}^2), \tag{4.2}$$

*where $\sigma_{k,+}^2 = \alpha(1-\alpha)p_k \int K^2(v)dv/[p_k p(\theta_\alpha^c(x)|x)]^2$, $\sigma_{k,-}^2 = \alpha(1-\alpha)p_{k-1} \int K^2(v)$
$dv/[p_{k-1} p(\theta_\alpha^c(x)|x)]^2$, and $N^+(0, \sigma_1^2) + N^-(0, \sigma_2^2)$ denotes the two-piece normal
distribution function $\Phi(\sigma_1 t)I(t > 0) + \Phi(\sigma_2 t)I(t < 0)$, with $\Phi(\cdot)$ the distribution
function of $N(0,1)$.*

*(iii) $\forall \alpha \in (0,1) \setminus \{P_k : k \in \mathbb{N}_0\}$, or $\alpha \in \{P_k : k \in \mathbb{N}_0\}$, $\hat{\theta}_\alpha(x) - \theta_\alpha(x) \xrightarrow{D} B(0)$; or
$\hat{\theta}_\alpha^c(x) - \theta_\alpha^c(x) \xrightarrow{D} B(0.5)$.*

In practice, the unknown quantities p_k, $p(x)$ and $p(x, \theta_\alpha^c(x))$ for given α can
be estimated by

$$\hat{p}_k = \sharp\{i : (X_i, Y_i) = (x, k)\}/n, \quad \hat{p}(x) = \sharp\{i : X_i = x\}/n, \quad \text{and} \quad p(x, \hat{\theta}_\alpha^c(x)),$$

where $\hat{\theta}_\alpha^c(x)$ is given by (3.5). Let $\hat{\sigma}^2$ be an estimator of σ^2 with $p(x)$ and
$p(x, \theta_\alpha^c(x))$ replaced by $\hat{p}(x)$ and $p(x, \hat{\theta}_\alpha^c(x))$. Set $\hat{\sigma}_{k,+}^2$ and $\hat{\sigma}_{k,+}^2$ accordingly. For
fixed x, let n_x be the number of values x taken on by the X_i's, $n_{k|x}$ be the number
of (Y_i, X_i)'s with $X_i = x$ and $Y_i = k$.

Corollary 1. *If A.1–A.4 hold, $n_x \to \infty$ and $n_{k|x} \to \infty$ as $n \to \infty$, then Theorem
3 holds with σ^2, $\sigma_{k,+}^2$, and $\sigma_{k,-}^2$ replaced by $\hat{\sigma}^2$, $\hat{\sigma}_{k,+}^2$, and $\hat{\sigma}_{k,+}^2$, respectively.*

4.2 Rank-transformed data

Since $\tilde{F}_n^R(v|j) = F_n^R(v|j)$ for all v ($v = 1, \ldots, M; j = 1, \ldots, m$), $\tilde{F}_n^R(\cdot|j) \to$
$\tilde{F}(\cdot|j)$ iff $F_n^R(\cdot|j) \to F(\cdot|j)$. We impose the conditions:
B.1 $nh \to \infty$, with $h > 0$;
B.2 $\delta \to 0$;
B.3 $\int K^2(t)dt < \infty$;
B.4 $\delta = o((nh)^{-1/2})$.

Theorem 4. *Under B.1–B.3, $F_n^R(y|x) \xrightarrow{P} F(y|x)$ and $\tilde{F}_n^R(y|x) \xrightarrow{P} \tilde{F}(y|x)$.*

Theorem 5. *Under B.1–B.3, we have
(i) $\tilde{\theta}_\alpha^R(x) \xrightarrow{P} \theta_\alpha^c(x)$, $\forall \alpha \in (0,1)$;
(ii) $\tilde{\theta}_\alpha(x) \xrightarrow{P} \theta_\alpha(x)$, $\forall \alpha \in (0,1) \setminus \{P_k : k \in \mathbb{N}_0\}$.*

Theorem 6. *Under B.1, B.3, and B.4, the following hold.*
(i) $\sqrt{nh}(\tilde{F}_n^R(y|x) - \tilde{F}(y|x)) \xrightarrow{D} N(0, \sigma_1^2)$,
with $\sigma_1^2 = \tilde{F}(y|x)(1 - \tilde{F}(y|x))p^{-1}(x) \int K^2(v)dv$.
(ii) $\forall \alpha \in (0,1) \setminus \{P_k : k \in \mathbb{N}_0\}$,

$$\sqrt{nh}(\tilde{\theta}_\alpha(x) - \theta_\alpha(x)) \xrightarrow{D} N(0, \sigma^2),$$

with $\sigma^2 = (1 - \alpha) \int K^2(v)dv/p^2(x, \theta_\alpha(x))$.
(iii) If $\alpha = P_k$ *for some* $k \in \mathbb{N}_1$,

$$\sqrt{nh}(\tilde{\theta}_\alpha(x) - \theta_\alpha(x)) \xrightarrow{D} N^+(0, \sigma_{k,+}^2) + N^-(0, \sigma_{k,-}^2),$$

where $\sigma_{k,+}^2 = \alpha(1 - \alpha) \int K^2(v)dv/[p_k p(\theta_\alpha^c(x)|x)]^2$, $\sigma_{k,-}^2 = \alpha(1 - \alpha) \int K^2(v)dv/$
$[p_{k-1}p(\theta_\alpha^c(x)|x)]^2$.
(iv) $\forall \alpha \in (0,1) \setminus \{P_k : k \in \mathbb{N}_0\}$, *or* $\alpha \in \{P_k : k \in \mathbb{N}_0\}$, *we have* $\tilde{\theta}_\alpha(x) - \theta_\alpha(x) \xrightarrow{D}$
$B(0)$; *or* $\tilde{\theta}_\alpha(x) - \theta_\alpha(x) \xrightarrow{D} B(0.5)$.

Proofs of these theorems may be found in the Appendix.

In practice, $\tilde{F}(y|x)$ is estimated by $\tilde{F}_n^R(y|x)$, σ_1^2 by $\hat{\sigma}_1^2$ with $\tilde{F}(y|x)$ and $p^{-1}(x)$ replaced by $\hat{p}^{-1}(x)$ and $\tilde{F}_n^R(y|x)$. Denote $\hat{\sigma}^2$ accordingly, with $\theta_\alpha(x)$ and $\theta_\alpha^c(x)$ replaced by $\tilde{\theta}_\alpha(x)$ and $\tilde{\theta}_\alpha^R(x)$, and $\hat{p}(x)$ and $p(x, \hat{\theta}_\alpha(x))$ as in Corollary 1.

Corollary 2. *Under B.1–B.4 and the conditions on n_x and $n_{k|x}$ of Corollary 1, the conclusion of Theorem 6 holds.*

5. Practical Issues
5.1 Kernel selection

It is well-known that the bias of kernel estimates of pmfs for cells near the boundary of the sample space can incur increased bias. Reduced bias can be achieved by using boundary corrected kernel estimators. For discrete data, a kernel function devised to correct for boundary effects has been proposed by Rajagopalan and Lall (1995). The general form of this kernel is given by

$$K_d(u_j) = au_j^2 + b, \quad |u_j| \le 1, \tag{5.1}$$

where $u_j = (i - j)/h$ $(i, j \in \mathbb{N}_1)$ with i the point at which the kernel function is evaluated. The parabolic shape of (5.1) was inspired by the Epanechnikov kernel

Table 1. Expressions for the coefficients a and b for the discrete quadratic kernel $K_d(u_j) = au_j^2 + b$, $|u_j| \leq 1$, where $u_j = (i-j)/h$ with i the point at which the kernel is evaluated.

Region	Coefficients	
	a	b
$i > h + 1$	$\frac{3h}{1-4h^2}$	$\frac{-3h}{1-4h^2}$
$1 < i \leq h + 1$	$\frac{-6h^2}{(i-1+h)(i-2+h)(i-3+h)}$	$\frac{3(2-h+h^2-3i+i^2)}{(i-1-h)(i-2+h)(i-3+h)}$
$i = 1$ $(h > 1)$	$\frac{-6h}{h^2-1}$	$\frac{3}{h+1}$

Note: Based on Rajagopalan and Lall (1995), with corrections for their expressions for a and b for the regions $i > h+1$ and $1 < i \leq h+1$; their expressions for a and b with $i = 1$ have been simplified.

in the continuous case, which enjoys some optimality properties as opposed to other commonly used kernels. The coefficients a and b are functions of h. They can be obtained by solving i) $K_d(u_j) = 0$ for $|u_j| \geq 1$, ii) $\sum_{j=i-h}^{j=i+h} K_d(u_j) = 1$, and iii) $\sum_{j=i-h}^{j=i+h} K_d(u_j)u_j = 0$. Expressions for a and b are given in Table 1. Throughout the paper we adopt (5.1), but in the initial phase of the simulation study we experimented with (5.1), a triangular, and a rectangular kernel function. In the latter two cases, the bias of the conditional quantile estimators was problematic for near-boundary bins with $n \leq 10,000$.

5.2 Grid size, band- and binwidth selection

To obtain good nonparametric estimates, we used cross-validation (CV) for jointly selecting band- and binwidth parameters, adapting the CV-approach used by Magee, Burridge, and Robb (1991). As an example, consider estimating (3.12). Given a fixed value of δ a value of h can be obtained by minimizing the loss function $L(h) = \sum_{u=1}^m \sum_{i=1}^n I(\tilde{X}_i = x_u^*)\rho_\alpha(Y_i - \tilde{\theta}_\alpha^{(-i)}(x_u^*))$, where $\rho_\alpha(u) = \alpha u I(u > 0) + (\alpha - 1)u I(u < 0)$ is the so-called "check" function, and $\tilde{\theta}^{(-j)}(\cdot)$ is the "delete-one" conditional quantile estimate.

To avoid summing over n terms, it is convenient to subtract $L^* = \rho_\alpha(Y_i - \breve{\theta}_\alpha(x_u^*))$ from $L(h)$, where $\breve{\theta}_\alpha(x_u^*)$ is some quantile estimate at x_u^* that does not vary with h. Let n_{1u} (n_{4u}) be the number of observations with $Y_i < \min\{\tilde{\theta}_\alpha(x_u^*), \breve{\theta}_\alpha(x_u^*)\}$ $(Y_i > \max\{\tilde{\theta}_\alpha(x_u^*), \breve{\theta}_\alpha(x_u^*)\})$, when $I(\tilde{X}_i = x_u^*) = 1$. Similarly, let n_{2u} and n_{3u} denote the number of observations falling in the interval $(\min\{\tilde{\theta}_\alpha(x_u^*), \breve{\theta}_\alpha(x_u^*)\}, \max\{\tilde{\theta}_\alpha(x_u^*), \breve{\theta}_\alpha(x_u^*)\})$ when, respectively, $\tilde{\theta}_\alpha(x_u^*) > \breve{\theta}_\alpha(x_u^*)$ and $\tilde{\theta}_\alpha(x_u^*) < \breve{\theta}_\alpha(x_u^*)$ with $I(\tilde{X}_i = x_u^*) = 1$. Then, rewriting $L(h) - L^*$ and

replacing Y_i by $\bar{Y}_u = \frac{1}{2}(\tilde{\theta}_\alpha(x_u^*) + \breve{\theta}_\alpha(x_u^*))$, gives the loss function

$$\sum_{u=1}^{m}[n_{1u}(1-\alpha)\{\tilde{\theta}_\alpha(x_u^*) - \breve{\theta}_\alpha(x_u^*)\} + n_{2u}I(\tilde{\theta}_\alpha(x_u^*) > \breve{\theta}_\alpha(x_u^*))(\alpha\breve{\theta}_\alpha(x_u^*)$$
$$- \bar{Y}_u + (1-\alpha)\tilde{\theta}_\alpha(x_u^*)) + n_{3u}I(\tilde{\theta}_\alpha(x_u^*) < \breve{\theta}_\alpha(x_u^*))(-(1-\alpha)\breve{\theta}_\alpha(x_u^*)$$
$$- \alpha\tilde{\theta}_\alpha(x_u^*) + \bar{Y}_u) + n_{4u}\alpha\{\breve{\theta}_\alpha(x_u^*) - \tilde{\theta}_\alpha(x_u^*)\}]. \tag{5.2}$$

A practical band- and binwidth approach involves the following steps.

1. Consider the CV criterion

$$\text{CV}(\delta) = \sum_{i=1}^{n} \rho_\alpha(Y_{(i)} - \breve{\theta}_\alpha^{(-i)}(x_u^*)),$$

   where $\breve{\theta}_\alpha^{(-j)}(\cdot)$ is an unsmoothed estimator of $\theta_\alpha(\cdot)$ given the sample $\{(\tilde{X}_i, R_i)$ $| 1 \le i \le n, i \ne j\}$. Select a prespecified range of grid sizes M, giving rise to a set of binwidth values $\mathcal{D}$. Choose the binwidth $\delta_{\text{cv}} = \arg\min_{\delta \in \mathcal{D}}\{CV(\delta)\}$.

2. Given δ_{cv} from Step 1, choose the bandwidth parameter to minimize (5.2).

3. Repeat Steps 1 and 2 with h_{cv} obtained from Step 2, and with the unsmoothed estimator of the CDF in Step 1 replaced by the binned kernel-smoothed conditional CDF (3.9).

6. Simulations

In this section we report on the simulation of the performance of $\hat{\theta}_\alpha(\cdot)$ using uncorrelated and positively correlated, uniformly distributed discrete bivariate random variables X and Y, using a bivariate Gaussian copula with a given correlation parameter ρ. Assume that X (Y) is distributed over the support $S_x = \{1, 2, \ldots, I_x\}$ ($S_y = \{1, 2, \ldots, I_y\}$), with I_x (I_y) a positive integer, according to the pmf $p(x) = 1/I_x$ ($p(y) = 1/I_y$) for $x \in S_x$ ($y \in S_y$) and zero elsewhere. The support of (X, Y) is $S_x \times S_y$. Then it may be deduced from results in Nelsen (1987) that the maximum feasible correlation between X and Y is $(I_y/I_x)\{(I_x^2 - 1)/(I_y^2 - 1)\}^{1/2}$. Hence, with $X_i \sim U[1, 10]$ and $Y_i \sim U[1, 100]$, the correlation parameter becomes 0.995. For each choice of n we generated $R = 10,000$ random samples, and for each n conditioning is based on each $\tilde{X} = x_u^*$
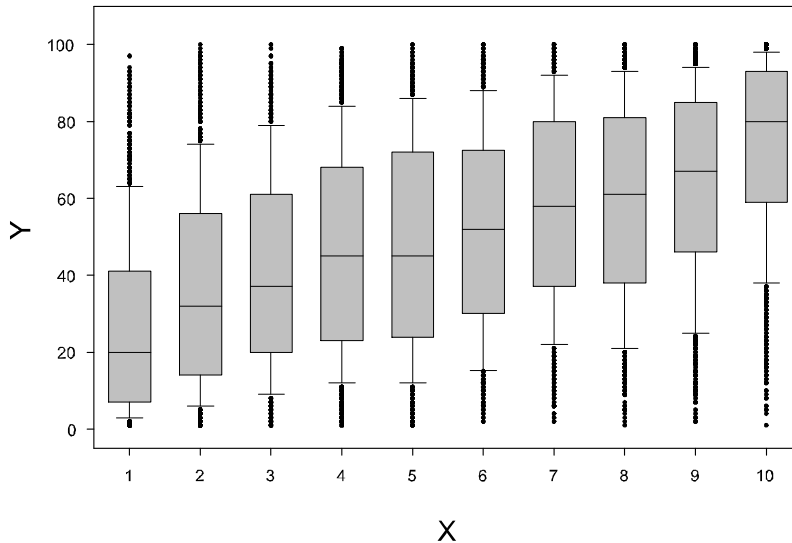
Figure 2. Boxplots of a simulated correlated dataset with $X \sim U[1,10]$ and $Y \sim U[1,100]$; $n = 10,000$, $\rho = 0.6$.

value. Values for ρ were set at $\rho = 0$, 0.2, 0.4, and 0.6, reflecting common circumstances. This setup resembles the empirical application in Section 7, with a small number of distinct covariates as opposed to a relatively larger number of response values. Figure 2 shows boxplots of the conditional distribution of Y given values of X for a typical simulated dataset of size $n = 10,000$ with $\rho = 0.6$. It can be seen that the conditional distribution of Y is skewed to the right (left) for X taking values at the lower (higher) boundary region. For $\rho = 0.2$ skewness of the underlying conditional distribution is less pronounced, but still present.

6.1 Performance of the untransformed quantile estimator

To abstract from the issue of binwidth selection, we evaluated the precision of $\hat{\theta}_\alpha(\cdot)$ by taking grid sizes $M = 30$, 40, and 50. So in Step 1 of the CV-algorithm δ was held constant, while in Step 2 we selected the value of h_{CV} from the set $\{2, 3, \ldots, 20\}$. We only report simulation results for $\alpha = 0.5$ (median), because a pilot study showed that similar conclusions could be reached with other quantile values. Overall, the optimal CV-selected bandwidth value was not very sensitive

Table 2. Ratios of the empirical MSEs (averaged over $R = 10,000$ replications) of $\hat{\theta}_{0.5}(x_u^*)$ relative to the CQR estimator and, in parentheses, relative to the "naive" estimator; $X \sim U[1, 10]$, $Y \sim U[1, 100]$, $M = 40$.

| x_u^* | $\rho = 0$ | | | $\rho = 0.2$ | | |
	$n = 5,000$	$n = 10,000$	$n = 20,000$	$n = 5,000$	$n = 10,000$	$n = 20,000$
1	2.44(0.95)	2.13(0.90)	1.81(0.85)	0.80(0.97)	0.49(0.95)	0.26(0.95)
2	3.24(0.94)	2.64(0.91)	2.14(0.86)	3.13(0.93)	2.58(0.89)	2.00(0.84)
3	4.21(0.94)	3.29(0.91)	2.39(0.86)	2.62(0.95)	1.73(0.94)	1.08(0.91)
4	5.20(0.94)	3.88(0.91)	2.62(0.85)	6.06(0.94)	4.92(0.90)	3.58(0.85)
5	6.05(0.94)	4.46(0.92)	2.62(0.85)	8.41(0.94)	6.94(0.91)	5.87(0.84)
6	5.90(0.95)	4.31(0.91)	2.67(0.85)	4.19(0.96)	2.68(0.91)	1.55(0.87)
7	4.96(0.94)	4.03(0.91)	2.47(0.86)	1.89(0.95)	1.14(0.90)	0.62(0.86)
8	4.15(0.93)	3.35(0.90)	2.37(0.86)	1.02(0.92)	0.61(0.87)	0.35(0.82)
9	3.21(0.93)	2.72(0.91)	2.05(0.85)	1.34(0.94)	0.80(0.92)	0.45(0.85)
10	2.45(0.94)	2.14(0.90)	1.79(0.86)	1.79(0.90)	1.39(0.85)	1.08(0.80)
	$\rho = 0.4$			$\rho = 0.6$		
1	0.30(0.96)	0.17(0.95)	0.09(0.93)	0.18(0.98)	0.10(0.99)	0.06(0.98)
2	1.05(0.86)	0.60(0.92)	0.34(0.86)	0.55(0.90)	0.31(0.83)	0.18(0.76)
3	0.87(0.93)	0.48(0.95)	0.26(0.92)	0.66(0.91)	0.36(0.84)	0.21(0.77)
4	1.77(0.96)	0.98(0.96)	0.54(0.94)	1.81(0.90)	1.01(0.86)	0.61(0.80)
5	9.31(0.95)	8.42(0.87)	8.06(0.80)	7.20(0.95)	4.31(0.92)	2.49(0.92)
6	4.21(0.90)	2.44(0.94)	1.40(0.94)	1.68(0.91)	0.98(0.86)	0.54(0.78)
7	0.73(0.84)	0.43(0.86)	0.24(0.78)	0.65(0.96)	0.33(0.94)	0.18(0.91)
8	0.44(0.95)	0.25(0.85)	0.14(0.79)	0.31(0.95)	0.16(0.93)	0.08(0.90)
9	0.48(0.94)	0.26(0.86)	0.15(0.81)	0.26(0.94)	0.14(0.91)	0.08(0.88)
10	0.65(0.92)	0.42(0.79)	0.28(0.70)	0.45(0.78)	0.32(0.70)	0.25(0.65)

to the choice of n with a maximum average (across all $R = 10,000$ replications) value of about 11 and a maximum average standard deviation of about 6. With $\rho = 0$, $\theta_{0.5}(x_u^*) = 50$ for all values $x_u^* = \{1, 2, \ldots, 10\}$. For $\rho = 0.2$, 0.4, and 0.6, $\theta_{0.5}(\cdot)$'s were calculated on the basis of 10,000 independently sampled, but paired correlated uniformly distributed discrete random variables with samples of size 30,000. These "theoretical" quantiles are included in Table 3, columns 2 and 9.

Our measure of precision is the empirical mean squared error (MSE) of the untransformed conditional quantile estimates averaged over all replications. We considered two estimators: (a) the conditional quantile regression (CQR) estimator of Machado and Santos Silva (2005), for discrete-continuous data; (b) the unsmoothed "naive" conditional quantile estimator, that groups the data according to the values of the covariates and assumes that the underlying distribution
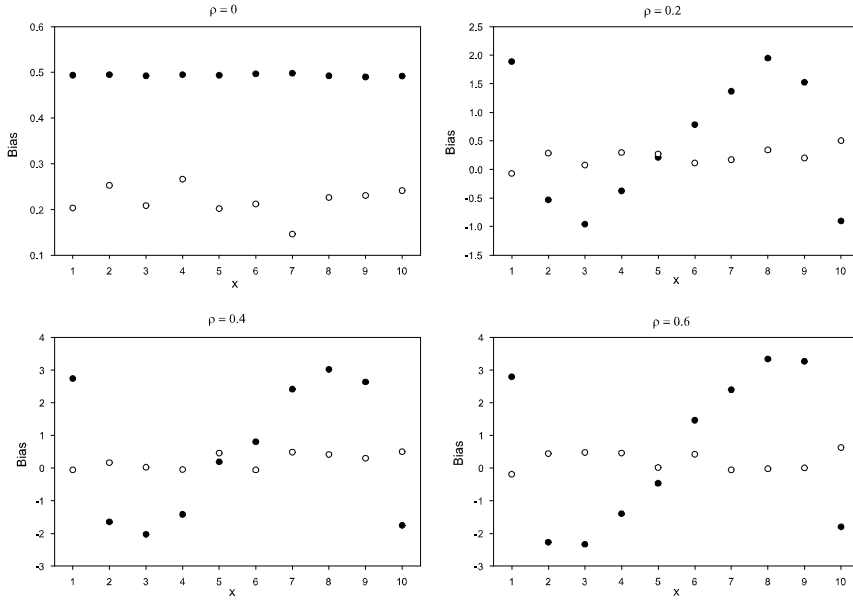
Figure 3. Bias of the CQR estimator (black circles) and the binned conditional quantile estimator $\hat{\theta}_{0.5}(\cdot)$ (white circles) averaged over $R = 10,000$ replications; $X \sim U[1, 10]$, $Y \sim U[1, 100]$, $M = 40$, $n = 5,000$.

for each resulting dataset is continuous. Thus the numbers in Table 2 represent the relative improvement attained by $\hat{\theta}_{0.5}(\cdot)$ relative to the CQR estimator and, in parentheses, the relative improvement attained by $\hat{\theta}_{0.5}(\cdot)$ relative to the "naive" estimator. To conserve space, Table 2 only contains results for $M = 40$.

The results show that across all covariates X and sample sizes n, the CQR estimator achieved the lowest empirical MSE when $\rho = 0$. However, when both ρ and n increase in value, the $\hat{\theta}_{0.5}(\cdot)$ estimator performed markedly better than the CQR estimator, apart for covariate values in the range [4, 6]. In particular, the MSE of the CQR estimator was dominated by increased positive bias when X took values at the lower boundary region. As an example, Figure 3 shows the bias of both conditional quantile estimators for $n = 5,000$. We see that, for all values ρ and $x_u^* \neq 5$, the absolute bias of the CQR estimator was substantially higher than the absolute bias of $\hat{\theta}_{0.5}(\cdot)$. At $x_u^* = 5$, however, the difference between both estimators was minimal, suggesting that the CQR estimator is only feasible if the conditional distribution of Y, given values of X, is not too skewed.

A much clearer picture about the usefulness of $\hat{\theta}_{0.5}(\cdot)$ emerges from the relative improvement attained by this estimator relative to the infeasible "naive" estimator. In each case, the numbers in parentheses in Table 2 show that $\hat{\theta}_{0.5}(\cdot)$ had lower empirical MSE than the "naive" estimator. In cases where $n = 5,000$, the difference was minor across almost all values of ρ. But, as n increased, the difference was quite substantial. The largest gains were for $\rho = 0.4$, and 0.6 at $x_u^* = 10$, when $n = 20,000$. Thus meaningful improvements in estimation efficiency can be expected when using the untransformed binned conditional quantile estimator if data are correlated and the sample size is large.

6.2 Confidence intervals and coverage probabilities

Theorems 3 and 6 can be used to construct large-sample confidence interval (CIs) for $\theta_\alpha(\cdot)$ at a given confidence level ξ. Here we focus on the practicality of the asymptotic result (4.1). For $K(\cdot)$ we selected the Gaussian kernel. There is no simple rule for choosing the bandwidth h. Its choice depends on the sample size, the value of the covariate, and the shape of the empirical (a)symmetric distribution of the data. We simply replaced h by $\hat{h} = Cn^{-1/5}\sigma_{Y|X}/\log(n)$ with $C = 0.01, 0.02, \ldots, 1$ a set of constants, and with $\sigma_{Y|X}$ the conditional variance of $Y|X = x$. This choice of h satisfies Condition A.4.

Note that for $\rho = 0$, we have $\sigma_{Y|X} = \sqrt{(I_y^2 - 1)/12}$. For $\rho \neq 0$, the "theoretical" values of $\sigma_{Y|X}$, $p(x)$ and $p(x,y)$ were, as before, based on $R = 10,000$ independently sampled, but paired correlated uniformly distributed discrete random variables with samples of size 30,000. Let z_ξ denote the $100(1-\xi)$ percentile of the standard normal distribution. Now for each pair $(x_u^*, \theta_\alpha(x_u^*))$ $(u = 1, \ldots, 10)$, correlation parameter ρ, sample size n, and value C, the performance of the CIs was assessed by recording the proportion of times the theoretical conditional quantiles $\theta_\alpha(\cdot)$ were contained in the interval

$$\hat{\theta}_\alpha(x_u^*) \pm z_\xi \sqrt{\alpha(1-\alpha)p(x_u^*) \int K^2(v)dv / p^2(x_u^*, \theta_\alpha(x_u^*))} \Big/ \sqrt{n\hat{h}}.$$

Let $\hat{P}(\theta_\alpha(x_u^*))$ denote the resulting proportion. Then, for each ρ and n, the "best" theoretical coverage probability (denoted by "True" in Table 3) is chosen as $\min_{C \in [0.01, 1.00]} \sum_{u=1}^{10} |\hat{P}(\theta_\alpha(x_u^*)) - 0.95|$, with $\alpha = 0.5$. The corresponding values of C vary between the ranges $[0.37, 0.54]$ ($\rho = 0$, $n = 5,000$) and $[0.63, 0.65]$

($\rho = 0.6$, $n = 10,000$). On balance, the coverage probabilities were satisfactory, with values very close to the nominal level for all values of ρ and n. Based on the above results, we conclude that a value of C in the range [0.47, 0.57] can result in good theoretical coverage probabilities across all values of ρ and n.

An alternative approach to compute empirical coverage probabilities and CIs is to use the bootstrap. Guerra, Polansky, and Schucany (1997) introduced this method for discrete univariate datasets. Here, as an example, we employ the sequence of bootstrap realizations of $\hat{\theta}_\alpha(x_u^*)$, $\{\hat{\theta}_\alpha^{\dagger b}(x_u^*)\}_{b=1}^B$, to estimate $P(\hat{\theta}_\alpha(x_u^*) \leq \theta_\alpha(x_u^*))$. We can do so by defining the bootstrap statistic

$$\widehat{P}(\hat{\theta}_\alpha^\dagger(x_u^*) \leq \theta_\alpha(x_u^*)) = \frac{1}{B} \sum_{b=1}^B I(\hat{\theta}_\alpha^{\dagger b}(x_u^*) \leq \hat{\theta}_\alpha(x_u^*)). \tag{6.1}$$

Thus a two-sided $(1 - \xi)$ CI can be based on finding the largest $\theta_\alpha^U(x_u^*)$ and smallest $\theta_\alpha^L(x_u^*)$ in a fixed and countable set of estimated conditional quantiles such that both $P(\hat{\theta}_\alpha^\dagger(x_u^*) \leq \theta_\alpha^L(x_u^*)) \leq \xi/2$ and $P(\hat{\theta}_\alpha^\dagger(x_u^*) \leq \theta_\alpha^U(x_u^*)) \geq 1 - \xi/2$ hold. In other words, given the discrete nature of the conditional quantiles, the set $S(x_u^*) = [\theta_\alpha^L(x_u^*), \theta_\alpha^U(x_u^*)]$ is the narrowest interval such that $P(\hat{\theta}_\alpha^\dagger(x_u^*) \in S(x_u^*)) \geq 1 - \xi$.

The bootstrapping took place as follows. At each simulation run (i) generate a random sample (X_i^*, Y_i^*) of size n with replacement from the empirical joint distribution of (X, Y), (ii) compute $\hat{\theta}_\alpha(\cdot)$, (iii) compute (6.1) based on $B = 500$ bootstrap samples drawn from the original sample, (iv) calculate the lower- and upper CI bounds, using a nominal level ξ and (6.1). Repeat this procedure over 1,000 independent runs. To save space, we only report results for the parameter configurations listed in Table 2.

Table 3 summarizes the averages of the empirical coverage probabilities obtained from (6.1) and averaged over 1,000 runs, and averages of the confidence sets $S(\cdot)$ (given in squared brackets). Recall that, by construction, we required that the empirical bootstrapped coverage probabilities are ≥ 0.95. Nonetheless, we may conclude that the empirical coverages were quite close to the nominal coverage probability. In addition, in all cases the CIs contained the true conditional quantile value. As expected, the length of $S(\cdot)$ decreased as n increased from $n = 5,000$ to $n = 10,000$, from a maximum average of about 9 to 6. In that case the minimum average length of $S(\cdot)$ went down from about 8 to 3. At

Table 3. Theoretical conditional quantile values $\theta_{0.5}(\cdot)$, averages of coverage probabilities of $\hat{\theta}_{0.5}(\cdot)$ based on Theorem 3(i) ("True"), averages of bootstrapped coverage probabilities of $\hat{\theta}_{0.5}(\cdot)$ with corresponding averages of upper- and lower CI limits in squared brackets; $X \sim U[1, 10]$, $Y \sim U[1, 100]$, $M = 40$, $R = 1,000$, $B = 500$, $1 - \xi = 0.95$.

| | | $\rho = 0$ | | | | | | $\rho = 0.2$ | | | | | |
| | | $n = 5,000$ | | | $n = 10,000$ | | | $n = 5,000$ | | | $n = 10,000$ | | |
x_u^*	$\theta_{0.5}$	True	Boot	$S(\cdot)$	True	Boot	$S(\cdot)$	$\theta_{0.5}$	True	Boot	$S(\cdot)$	True	Boot	$S(\cdot)$
1	50	0.959	0.955	[45, 53]	0.973	0.975	[46, 52]	37	0.976	0.950	[32, 39]	0.922	0.962	[33, 38]
2	50	0.957	0.969	[45, 53]	0.973	0.950	[46, 52]	42	0.965	0.966	[37, 45]	0.979	0.953	[39, 44]
3	50	0.962	0.957	[45, 53]	0.972	0.980	[46, 52]	45	0.965	0.971	[40, 48]	0.978	0.977	[41, 47]
4	50	0.957	0.958	[45, 53]	0.973	0.970	[46, 52]	47	0.961	0.958	[42, 50]	0.976	0.977	[43, 49]
5	50	0.955	0.955	[45, 53]	0.977	0.953	[46, 52]	49	0.959	0.964	[44, 52]	0.975	0.951	[45, 51]
6	50	0.960	0.960	[45, 53]	0.972	0.967	[46, 52]	51	0.956	0.955	[46, 54]	0.979	0.955	[47, 53]
7	50	0.959	0.961	[45, 53]	0.973	0.956	[46, 52]	53	0.960	0.961	[48, 56]	0.977	0.962	[50, 56]
8	50	0.960	0.969	[45, 53]	0.974	0.974	[46, 52]	55	0.964	0.972	[50, 58]	0.974	0.977	[51, 57]
9	50	0.957	0.951	[45, 53]	0.972	0.950	[46, 52]	58	0.965	0.968	[53, 61]	0.979	0.957	[55, 61]
10	50	0.958	0.962	[44, 53]	0.975	0.958	[46, 52]	63	0.972	0.974	[59, 66]	0.979	0.977	[60, 65]
		$\rho = 0.4$						$\rho = 0.6$						
1	27	0.977	0.974	[24, 30]	0.975	0.965	[24, 28]	21	0.967	0.963	[19, 23]	0.918	0.973	[18, 21]
2	36	0.932	0.979	[32, 40]	0.936	0.962	[32, 37]	32	0.954	0.961	[29, 35]	0.949	0.956	[29, 33]
3	41	0.973	0.975	[37, 45]	0.919	0.953	[38, 44]	38	0.927	0.968	[35, 42]	0.920	0.972	[35, 40]
4	45	0.968	0.972	[41, 49]	0.983	0.968	[40, 46]	43	0.973	0.969	[39, 47]	0.914	0.976	[40, 45]
5	48	0.962	0.967	[44, 52]	0.974	0.967	[45, 51]	48	0.974	0.962	[44, 52]	0.985	0.962	[45, 51]
6	52	0.963	0.953	[47, 55]	0.981	0.954	[47, 53]	52	0.971	0.973	[48, 56]	0.979	0.961	[49, 54]
7	55	0.962	0.968	[51, 59]	0.977	0.955	[52, 57]	57	0.980	0.968	[53, 61]	0.923	0.963	[53, 58]
8	59	0.969	0.976	[55, 63]	0.979	0.960	[56, 61]	62	0.934	0.952	[58, 65]	0.939	0.966	[59, 64]
9	64	0.929	0.983	[60, 68]	0.925	0.971	[61, 66]	68	0.959	0.956	[65, 71]	0.960	0.952	[65, 69]
10	73	0.967	0.966	[70, 76]	0.955	0.958	[70, 74]	79	0.940	0.953	[76, 81]	0.836	0.979	[77, 80]

$n = 25,000$, with $\rho = 0.6$, the average CI encompassed approximately 2 or 3 observations. Hence, the simulation evidence for $\hat{\theta}_{0.5}(\cdot)$ confirms the implications of the asymptotic results in Theorem 3. To provide a contrast, we also computed CIs for the rank-transformed conditional quantile estimator $\tilde{\theta}_{0.5}(\cdot)$. In all cases the interval lengths were longer, containing on average 2 additional observations. From Theorem 6 we know that $\tilde{\theta}_\alpha(\cdot)$ is less efficient, in the sense that its variance is bigger than the asymptotic variance of $\hat{\theta}_\alpha(\cdot)$. Our simulation results confirm this result.

7. Empirical Illustration

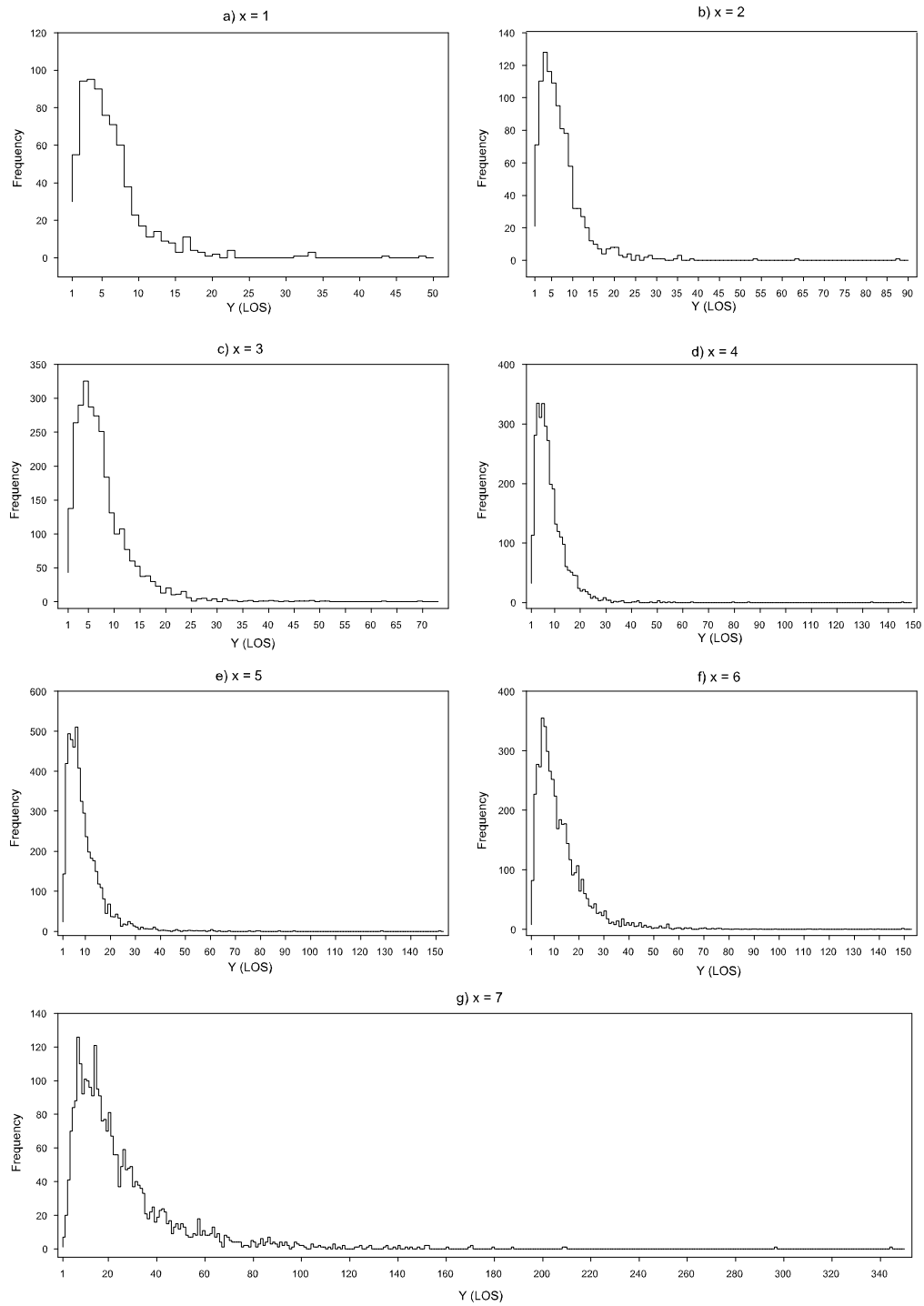We illustrate the method with an application using a large US database

Figure 4. Conditional frequency distributions of Y "Length of stay" (LOS) as a function of the covariate X "Severity".

about hospital patients who have congestive heart failure and are transferred to a tertiary facility. About 96% of these patients are living in New York state. The total dataset contains information on all medical conditions being identified by the medical staff for each of the years 2003–2005 ($n = 20,631$). We assume that the dataset has the nature of a population, and hence empirical conditional quantiles are considered as population quantities. One key response variable Y is "Length of stay" (Los), measured in days. This variable is used for management of hospital care, quality control, appropriateness of hospital use, and hospital planning. A suitable covariate X is "Severity", measured on a 7-point scale. This latter variable is largely a function of how complex the initial condition of a patient is. Increments of one are added for each confounding condition presented. Of course, if two conditions are present and both are life threatening the result could be four, but this is unusual. Similarly, a secondary condition like diabetes may not raise the variable "Severity" if it is generally associated with the primary condition like a heart attack. Figure 4 shows conditional frequency distributions for each covariate. Skewness (kurtosis) ranges between 2.9 (15.6) at $x = 3$ and 6.0 (83.9) at $x = 4$. The probability masses are fairly concentrated around the values of the conditional median, with large outliers at $x = 6$ and $x = 7$.

The empirical illustration of the performance of $\hat{\theta}_\alpha(\cdot)$ and $\tilde{\theta}_\alpha(\cdot)$ is based on $R = 10,000$ random samples of size $n = 5,000$ drawn without replacement from the full dataset. For both $\hat{\theta}_\alpha(\cdot)$ and $\tilde{\theta}_\alpha(\cdot)$ the optimal bandwidth values were chosen using the CV-criterion in Subsection 5.2 with M running from 55 to 200, and with h_{CV} in the range [2, 31]. The accuracy of each estimator was assessed by the average bias computed over the entire range of conditional quantile estimates. Table 4 shows these result for the first three conditional quartiles. Columns 2, 5, and 8 contain the "population" conditional quantiles. For this particular dataset these latter quantile estimates are the same as the values obtained by the "naive" quantile estimator, and plotted in Figure 1.

Note that across all values of x and α, the conditional quantile estimators performed well in terms of the highest percentage of zero bias. The effects on the bias of the estimators vary substantially with different values of the covariate X and quartiles α, showing both under- and overestimation. As an example, consider the case $x = 1$. At $\alpha = 0.75$ we see that both conditional quantile

Table 4. Average bias for $\hat{\theta}_\alpha(\cdot)$ and, in parentheses, $\tilde{\theta}_\alpha(\cdot)$; $n = 5,000$, $\theta_\alpha(\cdot)$ are "population" conditional quantiles.

x	$\theta_\alpha(\cdot)$	$\alpha = 0.25$	$\theta_\alpha(\cdot)$	$\alpha = 0.50$	$\theta_\alpha(\cdot)$	$\alpha = 0.75$
1	4	-0.658 (-0.506)	5	0.356 (0.439)	8	-0.015 (0.005)
2	4	-0.102 (0.002)	6	0.123 (0.166)	9	0.241 (0.247)
3	4	0.124 (0.180)	7	-0.338 (-0.105)	10	-0.045 (-0.046)
4	5	-0.439 (-0.173)	7	0.035 (0.040)	11	-0.049 (-0.029)
5	5	-0.047 (-0.000)	8	-0.213 (-0.055)	12	0.220 (0.243)
6	6	0.056 (0.054)	10	0.027 (0.045)	16	0.337 (0.303)
7	11	0.152 (0.227)	19	-0.251 (-0.287)	32	-0.260 (-0.829)

estimators had good performance, but this was not the case at $\alpha = 0.25$. On the other hand, at $x = 7$ and $\alpha = 0.75$, the ranked-based conditional quantile estimator performed worse than the untransformed conditional quantile estimator. Clearly, the shape of the conditional distribution has an impact on the performance of the estimators. However, removing five outlying observations at $x = 7$ from the sample, we noticed no improvement in the bias results. Basically, the above observations also apply to samples of size $n = 10,000$ although, in the latter case, the bias of the conditional quantile estimators was in general smaller than the bias of these estimators when $n = 5,000$.

When we estimated the full dataset, without resampling, both conditional quantile estimators showed zero bias results for almost all values of x and α. For $\hat{\theta}_\alpha(\cdot)$ the agreement between "population" and estimation results was less good at $x = 1$, $\alpha = 0.50$, at $x = 2$, $\alpha = 0.75$, and at $x = 6$, $\alpha = 0.75$. In all cases we noted a positive bias of one observation. For $\tilde{\theta}_\alpha(\cdot)$ we obtained a negative bias of one observation at $x = 1$, $\alpha = 0.25$, and at $x = 31$, $\alpha = 0.75$.

8. Conclusions

In this paper, we offer two kernel-based methods for estimating conditional quantiles of pairwise correlated, discrete random variables. Both methods make use of the local structure through pre-binning the data. Since grid counts need to be computed only once for the life of a dataset, large gains in computational efficiencies can be achieved. In particular, jointly with the introduction of a practical band- and binwidth selection procedure, we showed that our kernel methods can be applied to the large datasets that appear in practice.

Results from simulations showed that the untransformed binned conditional quantile estimator achieved excellent estimation accuracy in terms of bias, MSE, and CI coverage. However, for long-tailed right skewed distributions, the rank-transformed conditional quantile estimator also produced good nonparametric estimates, having the advantage of distributing the data more evenly across the set of bins. In addition, compared to the CQR estimator and the "naive" estimator, the gains in using the binned conditional quantile estimators can be considerable when dealing with large correlated bivariate discrete datasets. Moreover, our explicit asymptotic CIs for both conditional quantile estimates can be used for fast computation of the intervals.

Acknowledgment

Appendix: Proofs

For ease of notation, we write $x \equiv x_u^*$ throughout the Appendix. Unless otherwise stated, all summations are from 1 to n.

Proof of Theorem 1. Let $\hat{F}_n(y|x)$ be the Nadaraya-Waston estimator of $\tilde{F}(y|x)$ based on the original data Z_i's, i.e. $\hat{F}_n(y|x) = \sum_i K((x - X_i)/h)I(Z_i \leq y)/\sum_i K((x - X_i)/h)$ with $y \in \mathbb{R}$. Since $\tilde{F}(y|x) = F(y|x)$ and $\tilde{F}_n(y|x) = F_n(y|x)$ for all $y \in \mathbb{N}_1$, we have

$$(F_n(y|x) - F(y|x))^2 = (\tilde{F}_n(y|x) - \tilde{F}(y|x))^2 \leq (\tilde{F}_n(y|x) - \hat{F}_n(y|x))^2$$
$$+ 2|\tilde{F}_n(y|x) - \hat{F}_n(y|x)||\hat{F}_n(y|x) - F(y|x)| + (\hat{F}_n(y|x) - F(y|x))^2.$$

By (A.1) and Theorem 1 in Stute (1986), $\sup_y |\hat{F}_n(y|x) - F(y|x)| \overset{a.s.}{\to} 0$, which implies $\sup_y E(\hat{F}_n(y|x) - F(y|x))^2 \to 0$,

and $\sup_y E\left(|\tilde{F}_n(y|x) - \hat{F}_n(y|x)||\hat{F}_n(y|x) - F(y|x)| \right) \to 0$.

Note that the definition of $c_{u,\ell}(z|x)$ does not depend on the ordered data. So

$$(\tilde{F}_n(y|x) - \hat{F}_n(y|x))^2 = \frac{(\tilde{L}_n - \hat{L}_n)^2}{[(nh)^{-1}\sum_i K((x - X_i)/h)]^2}$$

$$:= \frac{\left((nh)^{-1} \sum_i K((x-X_i)/h)C_{i,u}(z|x) - (nh)^{-1} \sum_i K((x-X_i)/h)I(Z_i \leq y) \right)^2}{[(nh)^{-1} \sum_i K((x-X_i)/h)]^2}.$$

Since $(nh)^{-1} \sum_i K((x-X_i)/h) \overset{a.s.}{\to} P(x) > 0$, $(nh)^{-1} \sum_i K((x-X_i)/h) > P(x)/2$ (a.s.) for large n. In $\tilde{L}_n$ the X_i's are the original data; let L_n be the counter part of $\tilde{L}_n$ based on the binned X_i's with binwidth δ. Then $E(\tilde{L}_n - \hat{L}_n)^2 \leq E(L_n - \hat{L}_n)^2$.

Thus under A.2 and A.3, as in Theorem 1 of González-Manteiga (1996), we have

$$
\begin{aligned}
E(\tilde{F}_n(y|x) - \tilde{F}(y|x))^2 &\leq \frac{4}{P^2(x)} E(\tilde{L}_n - \hat{L}_n)^2 \\
&\leq \frac{4}{P^2(x)} E(L_n - \hat{L}_n)^2 = \frac{4}{P^2(x)} [O(h^2) + o(\delta^2)].
\end{aligned}
$$

The right hand side above is independent of y, which gives the desired result.

Proof of Theorem 2. (i) For $\epsilon > 0$, we have $\tilde{F}(\theta^c_\alpha(x) - \epsilon|x) < \alpha < \tilde{F}(\theta^c_\alpha(x) + \epsilon|x)$. Let S be the set of all events on which the results in Theorem 1 hold. Then for large n, on S we have

$$\tilde{F}_n(\theta^c_\alpha(x) - \epsilon|x) < \alpha < \tilde{F}_n(\theta^c_\alpha(x) + \epsilon|x).$$

Since $\tilde{F}(z|x) \geq t$ iff $z \geq \tilde{F}^{-1}(t|x)$, we have, on S for all large n, that $\theta^c_\alpha(x) - \epsilon \leq \hat{\theta}^c_\alpha(x) \leq \theta^c_\alpha(x) + \epsilon$. Since $\hat{\theta}^c_\alpha(x)$ is bounded on S for large n, and $\epsilon > 0$ is arbitrary, the conclusion holds.

(ii) It is a consequence of (i), as in the discussion of (ii) before Condition A.1.

Proof of Theorem 3. (i) Let $\hat{F}_n(y|x)$ be as given in the proof of Theorem 1. Note A.4 implies A.1 and A.2, so as in the proof of Theorem 1, $\tilde{F}_n(y|x) =$

$\hat{F}_n(y|x) + o_P((hn)^{-1/2})$, thus we have

$$P\left(\sqrt{nh}(\hat{\theta}_\alpha^c(x) - \theta_\alpha^c(x)) \leq t\right) = P\left(\hat{\theta}_\alpha^c(x) \leq \theta_\alpha^c(x) + (nh)^{-1/2}t\right)$$

$$= P\left(\tilde{F}_n(\theta_\alpha^c(x) + (nh)^{-1/2}t|x) \geq \alpha\right)$$

$$= P\left(\hat{F}_n(\theta_\alpha^c(x) + (nh)^{-1/2}t|x) \geq \alpha + o((hn)^{-1/2})\right)$$

$$= P\left(\frac{1}{nh}\sum_i K(\frac{x - X_i}{h})I(Z_i \leq \theta_\alpha^c(x) + (nh)^{-1/2}t)\right.$$

$$\geq \alpha\frac{1}{nh}\sum_i K(\frac{x - X_i}{h}) + o((hn)^{-1/2})\Big)$$

$$= P\left(\frac{1}{n}\sum_i \frac{1}{h}K(\frac{x - X_i}{h})[I(Z_i \leq \theta_\alpha^c(x) + (nh)^{-1/2}t) - \alpha] \geq o((hn)^{-1/2})\right)$$

$$:= P\left(\frac{1}{n}\sum_i A_{n,i} \geq o((hn)^{-1/2})\right).$$

Note that by A.4, $nh \to \infty$ and $h = o((nh)^{-1/2})$. Also, $P(Z < \theta_\alpha^c(x)|x) = \alpha$, so we have

$$E(A_{n,i}) = \frac{1}{h}\int\int K(\frac{y - x}{h})[I(z < \theta_\alpha^c(x) + (nh)^{-1/2}t) - \alpha]F(dy, dz)$$

$$= \int\int K(v)[I(z < \theta_\alpha^c(x) + (nh)^{-1/2}t) - \alpha]p(x + hv, dz)dv$$

$$= \int[I(z < \theta_\alpha^c(x) + (nh)^{-1/2}t) - \alpha]p(x, dz)(1 + O(h))$$

$$= P(Z < \theta_\alpha^c(x)|x)p(x) + p(x, \theta_\alpha^c(x))(nh)^{-1/2}t - \alpha p(x) + o((nh)^{-1/2})$$

$$= p(x, \theta_\alpha^c(x))(nh)^{-1/2}t + o((nh)^{-1/2}),$$

$$Var(A_{n,i}) = E(A_{n,i}^2) - E^2(A_{n,i}) \sim E(A_{n,i}^2)$$

$$= h^{-1}\int\int K^2(v)[I(z < \theta_\alpha^c(x) + (nh)^{-1/2}t)$$

$$- 2\alpha I(z < \theta_\alpha^c(x) + (nh)^{-1/2}t) + \alpha^2]p(x + hv, dz)dv$$

$$= \frac{1}{h}\alpha(1 - \alpha)p(x)\int K^2(v)dv + o(h^{-1}) := \frac{1}{h}\sigma_0^2 + o(h^{-1}).$$

Thus by the Central Limit Theorem, we get

$$P\left(\frac{1}{n}\sum_i A_{n,i} \geq o((hn)^{-1/2})\right)$$

$$= P\left(-\sqrt{nh}\sigma_0^{-1}\frac{1}{n}\sum_i (A_{n,i} - E(A_{n,i})) \leq \sigma_0^{-1}p(x,\theta_\alpha^c(x))t + o(1)\right)$$

$$\to \Phi(\sigma_0^{-1}p(x,\theta_\alpha^c(x))t).$$

Thus $\sqrt{nh}(\hat{\theta}_\alpha^c(x) - \theta_\alpha^c(x)) \xrightarrow{D} N(0,\sigma^2)$ with $\sigma^2 = \alpha(1-\alpha)p(x)\int K^2(v)dv/p^2(x,\theta_\alpha^c(x))$.

(ii) In this case, for $t > 0$, $E(A_{n,i}) = p_k p(\theta_\alpha^c(x)|x)(nh)^{-1/2}t + o((nh)^{-1/2})$, and $Var(A_{n,i}) \sim h^{-1}\alpha(1-\alpha)p_k \int K^2(v)dv$; for $t < 0$, $E(A_{n,i}) = p_{k-1}p(\theta_\alpha^c(x)|x)(n \times h)^{-1/2}t$, and $Var(A_{n,i}) \sim h^{-1}\alpha(1-\alpha)p_{k-1}\int K^2(v)dv$. The rest of the proof is the same as in (i).

(iii) This is a direct result of the discussion before Theorem 1.

Proof of Corollary 1. By the given condition we have $\hat{p}_k \to p_k$ (a.s.), $\hat{p}(x) \to p(x)$ (a.s.) and, by Theorem 2, $\hat{\theta}_\alpha^c(x) \xrightarrow{L_2} \theta_\alpha^c(x)$. The above convergences are all stronger than those in probability. Thus the results in Theorem 3 hold by Slutsky's Theorem.

Proof of Theorem 4. We only prove consistency for $F_n^R(y|x)$ to $F(y|x)$, that for $\tilde{F}_n^R(y|x)$ follows by the comment before Theorem 4. Rewrite $F_n^R(y|x) := F_n^R(v|j)$, for R_v being the smallest rank such that $Y_{(R_v)} \leq y$, and with $\tilde{X}_{(R_v)} = j$, as the standard form of a linear rank statistic $F_n^R(v|j) = \sum_i c_{n,i}a(R_i)$ with $c_{n,i} = \sum_u n_u^{-1}I(X_i = u)w_{n,u}$, $w_{n,u} = K((j-u)/h)/\sum_u K((j-u)/h)$, and $a(R_i) = \sum_{\ell=1}^v (1 - |\delta^{-1}R_i - (\ell-1)|)^+$. In the above we used the fact that $\sum_{u=1}^m n_u K((j-u)/h) = \sum_u K((j-u)/h)$.

We use the method and results in Hájek, Šidák, and Sen (1999). Let

$$\bar{c}_n = \frac{1}{n}\sum_i c_{n,i}, \quad \bar{a} = \frac{1}{n}\sum_i a(i), \quad \sigma_a^2 = \frac{1}{n-1}\sum_i (a(i) - \bar{a})^2.$$

Note that $(1 - |\delta^{-1}i - \ell|)^+ = [\delta - (\delta(\ell-1) - i)]/\delta$ for $\delta(\ell-2) \leq i < \delta(\ell-1)$ is $[\delta - (i - \delta(\ell-1))]/\delta$ for $\delta(\ell-1) \leq i < \delta\ell$; and is 0 elsewhere. So if $i \in ((k-1)\delta, (k+1)\delta)$ for some $k \leq v$, then $a(i) = \sum_{l=1}^v (1 - |\delta^{-1}i - \ell|)^+ = [(k\delta - i) + (i - (k-1)\delta)]/\delta = 1 = a^2(i)$, and $a(i) = 0$ for $i > v$. We have $\bar{a} = (v/n) + O(n^{-1})$,

$\sigma_a^2 = (v/n)(1 - (v/n)) + O(vn^{-2})$, and $\sum_i c_{n,i} = \sum_u w_{n,u} \frac{1}{n_u} \sum_i I(X_i = u) = \sum_u w_{n,u} = 1$. Since R_v is the smallest rank with $Y_{(R_v)} \leq y$ and with $\tilde{X}_{(R_v)} = x$, v is the number of the Y_i's with $Y_i \leq y$ and with $X_i = x$, so we have

$$\overline{a} = \frac{1}{n} \sum_i I(Y_i \leq y | X_i = x) + O(1/n) \overset{a.s.}{\to} F(y|x), \quad \sigma_a^2 \overset{a.s.}{\to} F(y|x)(1 - F(y|x)).$$

Also, with $j = x$,

$$\sum_i (c_{n,i} - \overline{c})^2 = \sum_u w_{n,u}^2 \frac{1}{n_u^2} (\sum_i I(X_i = u))^2 - \overline{c}^2 = \sum_u w_{n,u}^2 - 1/n$$

$$= (nh)^{-1} \frac{(nh)^{-1} \sum_u K^2((j-u)/h)}{\left((nh)^{-1} \sum_u K((j-u)/h) \right)^2} - 1/n.$$

By standard results on kernel estimation we have $(nh)^{-1} \sum_u K((j-u)/h) = p(x) + o(1)$, $(nh)^{-1} \sum_u K^2((j-u)/h) = p(x) \int K^2(v)dv + o(1)$. So we get, as $1/n = o((nh)^{-1})$,

$$\sum_i (c_{n,i} - \overline{c})^2 = (nh)^{-1} \frac{p(x) \int K^2(v)dv + o(1)}{p^2(x) + o(1)} - 1/n$$

$$= (nh)^{-1} p^{-1}(x) \int K^2(v)dv + o((nh)^{-1}).$$

Thus, by Theorem 3.3.3 in Hájek, Šidák, and Sen (1999, p. 61),

$$E(F_n^R(v|j)) = E(\overline{a} \sum_{i=1}^n c_{n,i}) = E(\frac{v}{n}) + O(1/n) \to F(y|x),$$

$$Var(F_n^R(v|j)) = \sigma_a^2 \sum_{i=1}^n (c_{n,i} - \overline{c})^2$$

$$= (nh)^{-1} F(y|x)(1 - F(y|x)) p^{-1}(x) \int K^2(v)dv + o((nh)^{-1}).$$

Now we have, $\forall \epsilon > 0$,

$$P\left(|F_n^R(y|x) - F(y|x)| \geq \epsilon \right) \leq P\left(|F_n^R(y|x) - E[F_n^R(y|x)]| \geq \epsilon/2 \right)$$

$$\leq \frac{4}{\epsilon^2} Var(F_n^R(y|x)) \sim \frac{4}{\epsilon^2 nh} F(y|x)(1 - F(y|x)) p^{-1}(x) \int K^2(v)dv \to 0.$$

This complete the proof of Theorem 4.

Proof of Theorem 5. The proof is similar to that of Theorem 2.

Proof of Theorem 6. We use the notations in the proof of Theorem 4.

(i) Let $\varphi(t) = 1$ if $t \le \tilde{F}(y|x)$ and 0 otherwise. Then it is easy to check that $\lim_n \int_0^1 [a(1 + [tn]) - \varphi(t)]^2 dt = 0$. Also $\int_0^1 \varphi^2(t) dt < \infty$, $\int_0^1 [\varphi(t) - \overline{\varphi}]^2 dt = \tilde{F}(y|x)(1 - \tilde{F}(y|x)) > 0$, where $\overline{\varphi} = \int_0^1 \varphi(t) dt = \tilde{F}(y|x)$. By definition we have $\tilde{F}_n^R(y|x) = F_n^R(y|x) + O(\delta)$, and $O(\delta) = o((nh)^{-1})$ by B.4. Thus by the linear rank statistic form of $F_n^R(y|x)$ as given in the proof of Theorem 4, Theorem 6.6.1 in Hájek, Šidák, and Sen (1999, p. 194), and the relationship $\tilde{F}_n^R(y|x) = F_n^R(y|x) + o((nh)^{-1})$, we have that $\tilde{F}_n^R(y|x)$ is asymptotically normal (μ_n, σ_n^2) with $\mu_n = E\tilde{F}_n^R(y|x) = \overline{a} + o((nh)^{-1/2})$, and $\sigma_n^2 = [\sum_u (c_{n,u} - \overline{c})^2] \int_0^1 [\varphi(t) - \overline{\varphi}]^2 dt$. Using results on $\overline{a}$ and $\sum_u (c_{n,u} - \overline{c})^2$ from the proof of Theorem 4, we get

$$\sqrt{nh}(\tilde{F}_n^R(y|x) - \tilde{F}(y|x)) \xrightarrow{D} N(0, \sigma_1^2),$$

with $\sigma_{1u}^2 = \tilde{F}(y|x)(1 - \tilde{F}(y|x))p^{-1}(x) \int K^2(v) dv$.

(ii) As in the proof of Theorem 3, we have

$$P\left(\sqrt{nh}(\tilde{\theta}_\alpha(x) - \theta_\alpha(x)) \le t\right) = P\left(\tilde{F}_n^R(\theta_\alpha(x) + (nh)^{-1/2}t|x) \ge \alpha\right).$$

As in the proof of Theorem 4, we have, with $p(y|x)$ being the density of $\tilde{F}(y|x)$,

$$E(\tilde{F}_n^R(\theta_\alpha(x) + (nh)^{-1/2}t|x)) = \tilde{F}(\theta_\alpha(x) + (nh)^{-1/2}t|x) + O(1/n)$$
$$= \tilde{F}(\theta_\alpha(x)|x) + p(\theta_\alpha(x)|x)(nh)^{-1/2}t + o((nh)^{-1/2}) + O(1/n)$$
$$= \alpha + p(\theta_\alpha(x)|x)(nh)^{-1/2}t + o((nh)^{-1/2}),$$

$$Var(\tilde{F}_n^R(\theta_\alpha(x) + (nh)^{-1/2}t|x)) = (nh)^{-1}\tilde{F}(\theta_\alpha(x) + (nh)^{-1/2}t|x)$$
$$\times (1 - \tilde{F}(\theta_\alpha(x) + (nh)^{-1/2}t|x))p^{-1}(x) \int K^2(v) dv + o((nh)^{-1})$$
$$= (nh)^{-1}\alpha(1 - \alpha)p^{-1}(x) \int K^2(v) dv + o((nh)^{-1}).$$

Applying Theorem 6.6.1 in Hájek, Šidák, and Sen (1999, p. 194) again to the linear rank statistic form of $\tilde{F}_n^R(\theta_\alpha(x) + (nh)^{-1/2}t|x)$, as in the proof of Theorem 4, we get

$$P\left(\tilde{F}_n^R(\theta_\alpha(x) + (nh)^{-1/2}t|x) \ge \alpha\right)$$

$$= P\left(\frac{E(\tilde{F}_n^R(\theta_\alpha(x) + (nh)^{-1/2}t|x)) - \tilde{F}_n^R(\theta_\alpha(x) + (nh)^{-1/2}t|x)}{\sqrt{Var(\tilde{F}_n^R(\theta_\alpha(x) + (nh)^{-1/2}t))}}\right.$$

$$\left. \leq \frac{p(\theta_\alpha(x)|x)t}{[\alpha(1-\alpha)p^{-1}(x)\int K^2(v)dv]^{1/2}} + o(1)\right) \to \Phi\left(\frac{p(x)p(\theta_\alpha(x)|x)}{[\alpha(1-\alpha)\int K^2(v)dv]^{1/2}}t\right),$$

so that $\sqrt{nh}(\tilde{\theta}_\alpha(x) - \theta_\alpha(x)) \xrightarrow{D} N(0, \sigma^2)$, with $\sigma^2 = \alpha(1-\alpha)\int K^2(v)dv/p^2(x, \theta_\alpha(x))$. (iii) and (iv) Proofs are similar to those of (ii) and (iii) in Theorem 3.

Proof of Corollary 2. Since by Theorems 4 and 5, $\tilde{F}_n^R(y|x) \xrightarrow{P} \tilde{F}(y|x)$, $\tilde{\theta}_\alpha^R(x) \xrightarrow{P} \theta_\alpha^c(x)$ and $\tilde{\theta}_\alpha(x) \xrightarrow{P} \theta_\alpha(x)$. The rest of the proof is similar to that of Corollary 1.

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